

PCA From Noisy Linearly Reduced Measurements

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joint work with Amit Singer and Tejal Bhamre

The Program in Applied and Computational Mathematics
Princeton University

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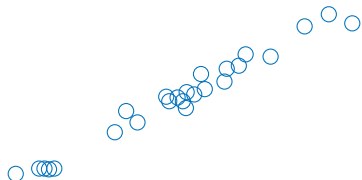


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Principal components analysis (PCA)

Given i.i.d. samples $\mathbf{x}_1, \dots, \mathbf{x}_n$ of some $\mathbf{x} \in \mathbb{R}^p$, estimate mean $\mathbb{E}[\mathbf{x}]$ and covariance $\text{Cov}[\mathbf{x}]$.

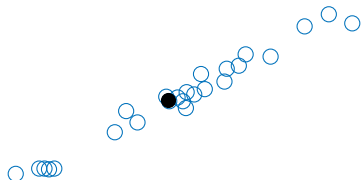
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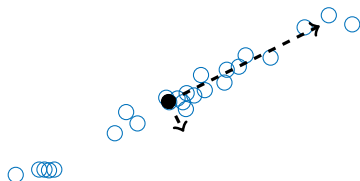
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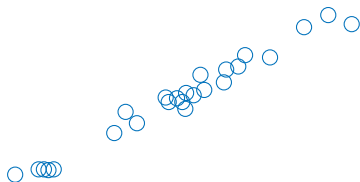
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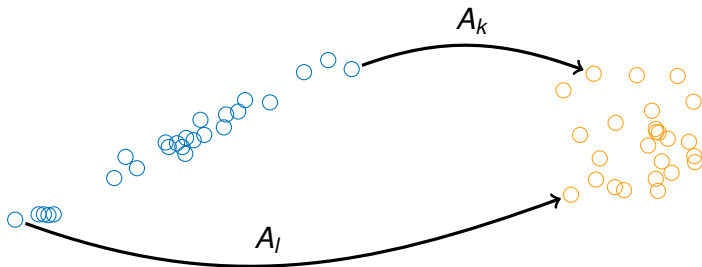
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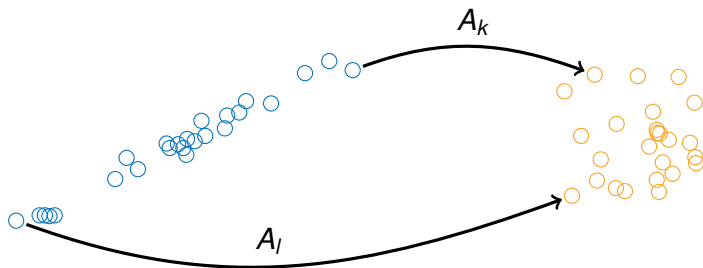
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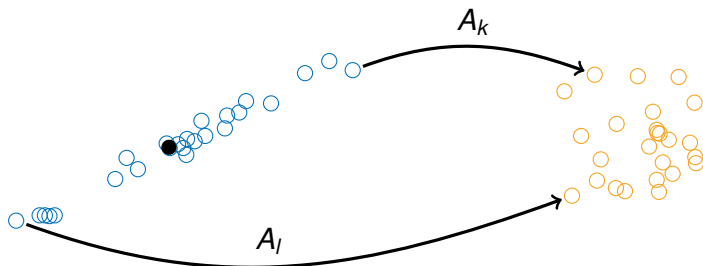


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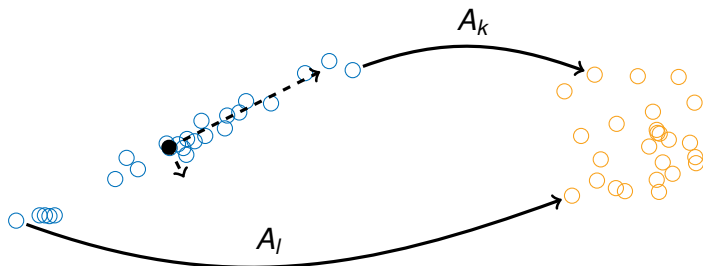


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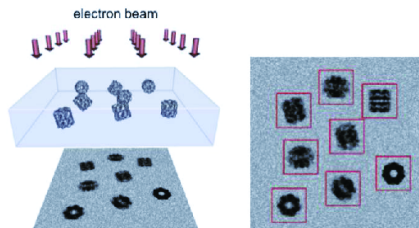
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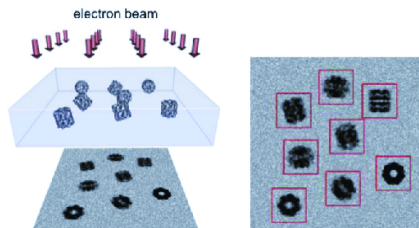


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Motivation: cryo-electron microscopy



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Write image \mathbf{y}_k as

$$\mathbf{y}_k = T_k P_k \phi_k + \mathbf{e}_k$$

where:

- ϕ_k is a three-dimensional molecular volume,
- P_k projects volume into an image and T_k filters it, and
- \mathbf{e}_k is measurement noise.

Application: deconvolution in noise

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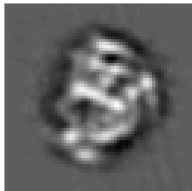
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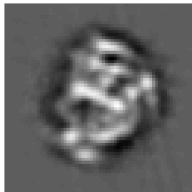


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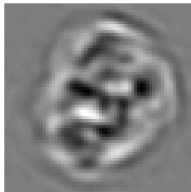
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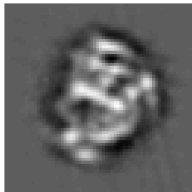


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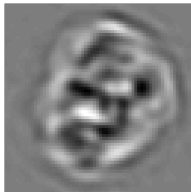
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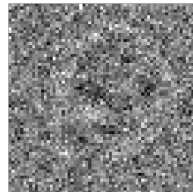
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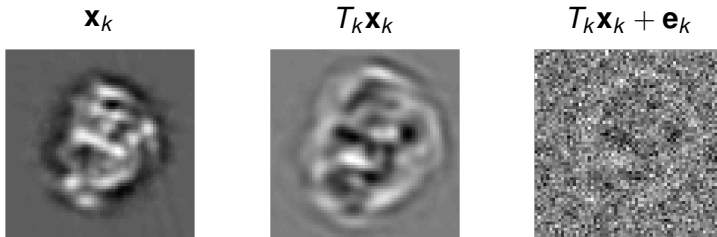
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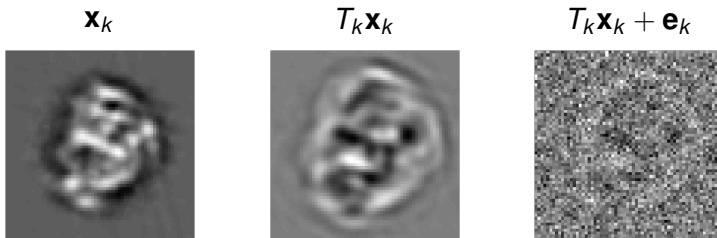


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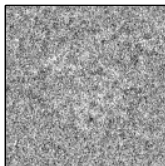


- Filtering $T_k : \mathbb{R}^p \rightarrow \mathbb{R}^p$ is singular or ill-conditioned.
- Using low-rank $\text{Cov}[\mathbf{x}]$, we can invert T_k and reduce effect of noise \mathbf{e}_k .

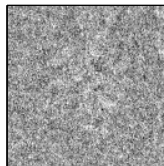
Application: heterogeneity

How to classify images from different molecular structures?

Class A



Class B¹

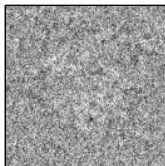


¹Images courtesy Joachim Frank (Columbia)

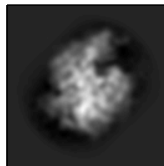
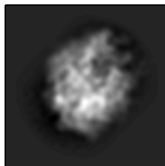
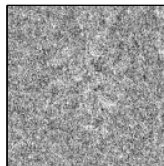
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- Aggregating large-scale datasets give accurate estimates – despite high noise.

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Least-squares estimator (mean)

- From $\mathbf{y}_k = \mathbf{A}_k \mathbf{x}_k + \mathbf{e}_k$, we have

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- Form least-squares estimator for $\mathbb{E}[\mathbf{x}]$

$$\boldsymbol{\mu}_n = \arg \min_{\boldsymbol{\mu}} \frac{1}{n} \sum_{k=1}^n \|\mathbf{y}_k - \mathbf{A}_k \boldsymbol{\mu}\|^2.$$

Least-squares estimator (covariance)

- Again $\mathbf{y}_k = \mathbf{A}_k \mathbf{x}_k + \mathbf{e}_k$ gives

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- Form least-squares estimator for $\text{Cov}[\mathbf{x}]$

$$\boldsymbol{\Sigma}_n = \arg \min_{\boldsymbol{\Sigma}} \frac{1}{n} \sum_{k=1}^n \left\| (\mathbf{y}_k - \mathbf{A}_k \boldsymbol{\mu}_n) (\mathbf{y}_k - \mathbf{A}_k \boldsymbol{\mu}_n)^T - (\mathbf{A}_k \boldsymbol{\Sigma} \mathbf{A}_k^H + \sigma^2 \mathbf{I}_q) \right\|_F^2.$$

Normal equations

- Mean estimator μ_n satisfies

$$\left(\frac{1}{n} \sum_{k=1}^n A_k^T A_k \right) \mu_n = \frac{1}{n} \sum_{k=1}^n A_k^T \mathbf{y}_k.$$

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- For covariance, $L_n(\Sigma_n) = B_n$, with $L_n : \mathbb{R}^{p \times p} \rightarrow \mathbb{R}^{p \times p}$ given by

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- Resulting linear system in p^2 variables can be solved efficiently using the conjugate gradient method.

Estimator properties

- Taking $A_k = I_p$ and $\sigma^2 = 0$, recover sample mean and covariance.

³Katsevich et al (2015)

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- Does not rely on a particular distribution of \mathbf{x} .
- With prior information on \mathbf{x} , can regularize by adding terms to least-squares objective.
- Both μ_n and Σ_n are consistent estimators³. For $n \rightarrow \infty$

$$\mu_n \xrightarrow{\text{a.s.}} \mathbb{E}[\mathbf{x}]$$

$$\Sigma_n \xrightarrow{\text{a.s.}} \text{Cov}[\mathbf{x}]$$

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High-dimensional PCA: Marčenko-Pastur

For pure Gaussian white noise of unit variance

$$\mathbf{y}_k = \mathbf{e}_k,$$

we have sample covariance $\frac{1}{n} \sum_{k=1}^n \mathbf{y}_k \mathbf{y}_k^T$.

High-dimensional PCA: Marčenko-Pastur

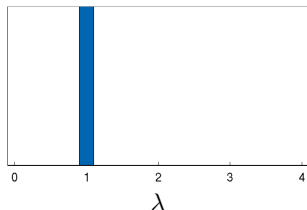
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Central limit theorem



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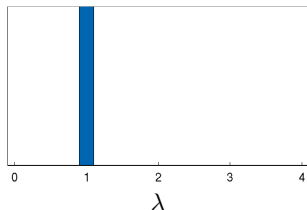
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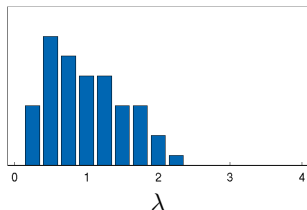
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$$n \asymp p$$

Marčenko-Pastur law



High-dimensional PCA: spiked covariance model

Both signal and noise

$$\mathbf{y}_k = \mathbf{x}_k + \mathbf{e}_k.$$

⁴Johnstone (2001)

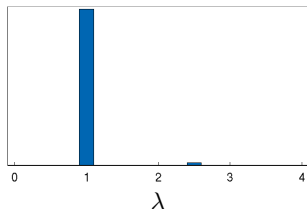
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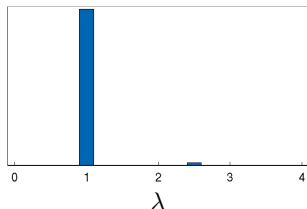
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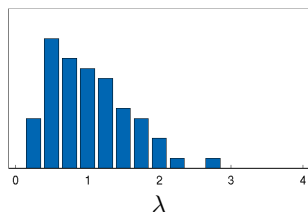
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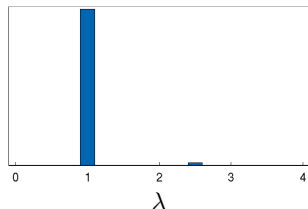
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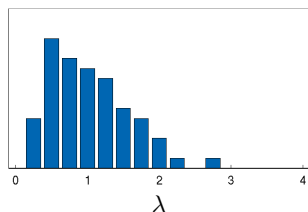
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Spiked covariance model⁴



Signal eigenvalues pop out of bulk when $\text{SNR} > \sqrt{p/n}$.

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High-dimensional PCA: shrinkage

To estimate $\text{Cov}[\mathbf{x}]$ from

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when $n \asymp p$, we apply shrinkage to eigenvalues of sample covariance⁵

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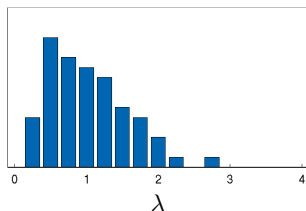
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Original



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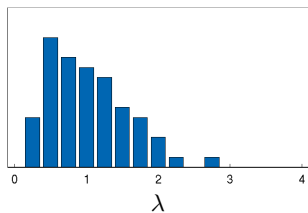
High-dimensional PCA: shrinkage

To estimate $\text{Cov}[\mathbf{x}]$ from

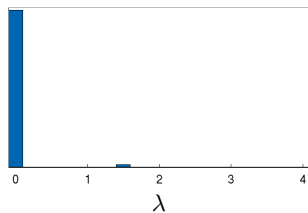
$$\mathbf{y}_k = \mathbf{x}_k + \mathbf{e}_k,$$

when $n \asymp p$, we apply shrinkage to eigenvalues of sample covariance⁵

Original



Shrinkage



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Shrinkage of B_n

- In clean case, $\mathbf{y}_k = A_k \mathbf{x}_k$ and

$$B_n = \frac{1}{n} \sum_{k=1}^n A_k^T A_k (\mathbf{x}_k - \boldsymbol{\mu}_n) (\mathbf{x}_k - \boldsymbol{\mu}_n)^T A_k^T A_k,$$

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- For large n , we then have

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- How do we estimate $\text{Cov}[\mathbf{A}_k^T \mathbf{A}_k \mathbf{x}_k]$ given noisy \mathbf{y}_k ?

Shrinkage of B_n (cont.)

- Colored noise

$$\mathbf{A}_k^T \mathbf{y}_k = \mathbf{A}_k^T \mathbf{A}_k \mathbf{x}_k + \underbrace{\mathbf{A}_k^T \mathbf{e}_k}_{\text{covariance } \mathbb{E}[\mathbf{A}_k^T \mathbf{A}_k]}.$$

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- Whiten by calculating

$$\mathbf{S} = \frac{1}{n} \sum_{k=1}^n \mathbf{A}_k^T \mathbf{A}_k \approx \mathbb{E}[\mathbf{A}_k^T \mathbf{A}_k]$$

and setting

$$\mathbf{z}_k = \mathbf{S}^{-1/2} \mathbf{A}_k^T (\mathbf{y}_k - \mathbf{A}_k \mu_n).$$

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- Calculate sample covariance, shrink

$$\rho \left(\sum_{k=1}^n \mathbf{z}_k \mathbf{z}_k^T \right)$$

Shrinkage of B_n (cont.)

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- Calculate sample covariance, shrink, and unwhiten

$$B_n = \mathbf{S}^{1/2} \rho \left(\frac{1}{n} \sum_{k=1}^n \mathbf{z}_k \mathbf{z}_k^T \right) \mathbf{S}^{1/2}.$$

Deconvolution in noise

- Recall noisy, filtered, image

$$\mathbf{y}_k = T_k \mathbf{x}_k + \mathbf{e}_k$$

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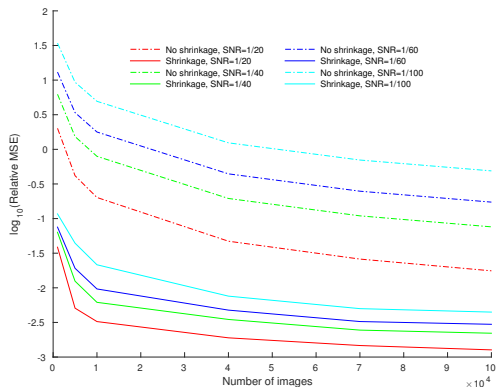
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- Using covariance estimation method, estimate $\text{Cov}[\mathbf{x}_k]$.
- Construct generalized Wiener filter and invert T_k – estimate \mathbf{x}_k from \mathbf{y}_k :

$$\Sigma_n T_k^T (T_k \Sigma_n T_k^T + \sigma^2 \mathbf{I}_q)^{-1} \mathbf{y}_k. \quad (1)$$

Effect of shrinkage on simulated data



Applying shrinkage to right-hand side B_n in $L_n(\Sigma_n) = B_n$ results in significant increase in accuracy for the covariance estimation.

Experimental results: TRPV1 (EMPIAR-10005)

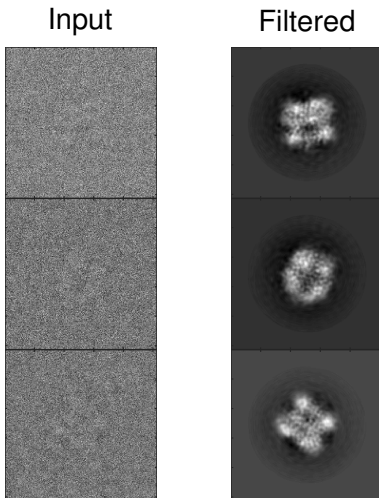
Dataset of 35645 projection images 256-by-256 pixels large.

Input



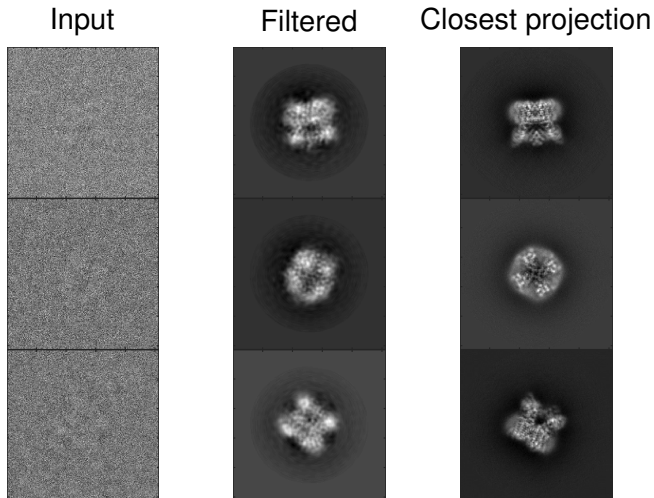
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classify \mathbf{y}_k according to molecular state \mathbf{x}_k .

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- We can invert $T_k P_k$ to find coordinates in subspace and cluster.

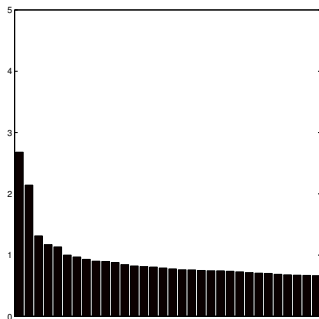
Experimental results: 70S ribosome

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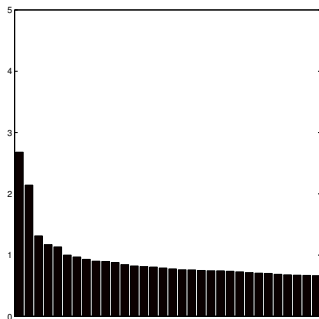
Largest 32 eigenvalues



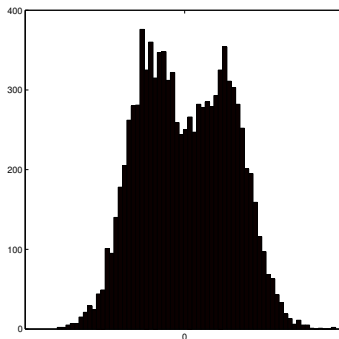
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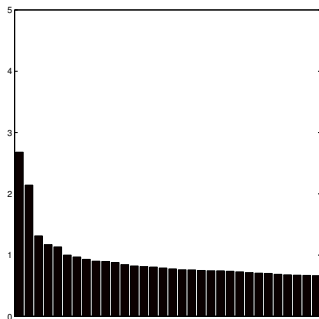
Coordinate histogram



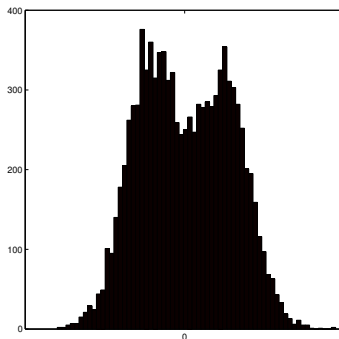
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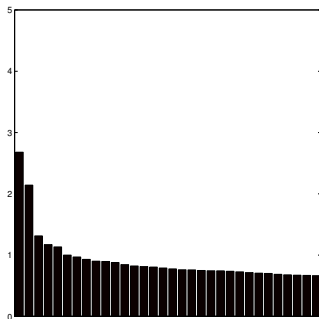


Clustering accuracy 89% with respect to dataset labeling.

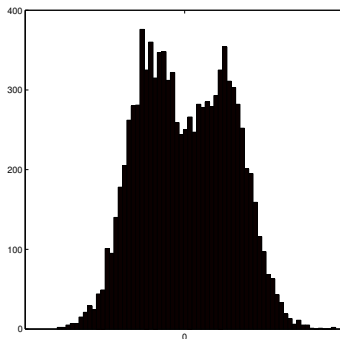
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Took 26 min. on a 2.7 GHz, 12-core CPU.

Conclusions

- Least-squares approach to covariance estimation from noisy partial measurements is a simple but powerful method to characterize the distribution of the underlying data.

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- In the high-dimensional regime, eigenvalue shrinkage can significantly improve the performance of the estimator.
- Covariance information can be leveraged to great effect in denoising and classification tasks such as those encountered in cryo-EM.

Current and future work

- How to incorporate constraints on covariance Σ_n , such as sparsity.

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- Understanding behavior of bulk noise distribution in Σ_n , not just in B_n .
- Application to other tasks, such as embryo development, magnetic resonance imaging, and matrix completion.

J. Andén, E. Katsevich, and A. Singer, "Covariance estimation using conjugate gradient for 3D classification in Cryo-EM," *12th IEEE International Symposium on Biomedical Imaging*, 2015.

T. Bhamre, T. Zhang, and A. Singer, "Denoising and covariance estimation of single particle cryo-em images," *Journal of structural biology*, vol. 195, no. 1, pp. 72–81, 2016.

E. Katsevich, A. Katsevich, and A. Singer, "Covariance matrix estimation for the Cryo-EM heterogeneity problem," *SIAM Journal on Imaging Sciences*, vol. 8, no. 1, pp. 126–185, 2015.