

Workshop on Modern Massive Data Matrices,
Palo Alto 2006.

General Thoughts : Bad historical accident
that Numerical and Scientific Computation and
Algorithms and Complexity do not have more
to do with each other.

NA has a couple of centuries work to offer
Alg.'s.

Alg.'s (once you get beyond our seeming ob-
session with poly time) has a lot to offer. Ran-
domization is certainly one of them....

Here simpler notion of **good** :

$$A^T A \approx R^T R.$$

Notation A is $m \times n$.

Number of rows in sample = s . ($s \ll m, n$.)

Quickly : Could mean polynomial time.

Here : Massive Matrices. Perhaps cannot be stored in full in RAM. [More generally, models of computation for handling massive data - eg. the **streaming** model.....

Quickly : In one or two passes thro' A .

Randomization will help.

Uniform random sample won't do : All but one row zero !!

Sample with probabilities depending on size of entries in row.

The **Length-squared distribution** : Pick rows with probabilities proportional to their **squared lengths** : Make s i.i.d. trials. In each trial, pick a row $A_{(i)}$ (the i th row of A) with

$$\text{Probability of picking row } i = \frac{|A_{(i)}|^2}{\|A\|_F^2}.$$

If $A_{(i)}$ is picked, include a **scaled** version : $A_{(i)}/\sqrt{sP_i}$ as the next row of R .

If all row lengths are equal, uniform sampling will do and no scaling is necessary.

[In fact, same if all row lengths are within $O(1)$ of each other.]

Two Properties of the sampling

$$\text{Unbiased } E(R^T R) = A^T A.$$

This distribution **minimizes** the **total variance**

$$E\|A^T A - R^T R\|_F^2.$$

[Measuring $E\|A^T A - R^T R\|_F^2$ greatly simplifies the expression.]

For most results, **approx length-squared** distribution, where probability of picking row i is at least $\frac{c|A_{(i)}|^2}{\|A\|_F^2}$ suffices.

— Frieze, K., Vempala (1998)

Many other properties of the distribution - fast SVD.....

How good is this sample ?

s is the number of sampled rows.

Lemma For every matrix A ,

$$E\|R^T R - A^T A\|_F^2 \leq \frac{1}{s}\|A\|_F^4.$$

Only interesting if

$$\frac{\|A\|_F^4}{\|A^T A\|_F^2}$$

is small.

Condition equivalent to

The top $O(1)$ singular values form $\Omega(1)$ part of the “spectrum” of A .

Above for $A^T A$ can be generalized to multiplying any two matrices. – Drineas, K.

$R^T R \approx A^T A$ implies the singular values of $R \approx$ the singular values of A . Can be quantified by Hoffman-Wielandt inequality.

More difficult questions Can one also say the same about the singular vectors of A, R ? Is there a sense in which

$$R \approx A?$$

No free lunch

We cannot hope to pick from any general $m \times n$ matrix, a set of $s \ll m, n$ rows to form an R with $R^T R$ close to $A^T A$. Call a matrix A a PCA matrix if for $k \in O(1)$:

$$\lambda_1(A^T A) + \lambda_2(A^T A) + \dots + \lambda_k(A^T A) \geq c \|A\|_F^2.$$

Then, above says : $E \|R^T R - A^T A\|_F^2 \leq \epsilon \|A^T A\|_F^2$ for $s \in O(1)$. Myriad applications of Principal Component Analysis (assume matrix is a PCA matrix or more strongly that they are numerically low-rank) include :

Consumer-Product matrices

Document-term matrices

Test scores- Students matrices....

TCS contribution : Low-rank approximations to matrices and their extensions to tensors can also help solve combinatorial optimization problems.

Approximating A itself

Suppose C is a random subset of s columns of A picked according to the length-squared distribution (and scaled as above) and R is a subset of s rows of A " " " . From just C, R , we can find an $s \times s$ matrix U such that

$$E\|A - CUR\|_F \leq \|A - A_{s^{1/5}}\|_F + \frac{4}{s^{1/5}}\|A\|_F,$$

$$E\|A - CUR\|_2 \leq \|A - A_{s^{1/5}}\|_2 + \frac{4}{s^{1/5}}\|A\|_F,$$

[where, A_k is the best rank k approximation to A and $\|A\|_2$ denotes the spectral norm.] –

Drineas, K., also Drineas, K., Mahoney.

$$\left(\begin{array}{c} \\ \\ A \\ \\ \end{array} \right) \approx \quad (2)$$

$$\left(\begin{array}{c} \\ \\ C \\ \\ \end{array} \right) \cdot \left(\begin{array}{c} \\ \\ U \\ \\ \end{array} \right) \cdot \left(\begin{array}{c} \\ \\ R \\ \\ \end{array} \right) \quad (3)$$

Sparsity preserved

Further **matrix-vector products** Ax can be approximated by $C(U(Rx))$.

Matrix Reconstruction

m users and n products. A_{ij} measures the preference of user i for product j .

Suppose we have observed some entries of the matrix. Can we infer the other entries? [So, having observed some market behaviour, we want to recommend to users what they would like.]

[Recommendations Systems / Collaborative filtering]

Azar, Fiat, Karlin, McSherry and Saia

Achlioptas and McSherry

Drineas, Kerenidis and Raghavan

Achlioptas and McSherry's algorithm :

p probability. Independently for each entry A_{ij} of matrix, replace it with A_{ij}/p with probability (w.p) p and 0 with probability $1 - p$. So, number of non-zero entries reduced by a factor of p .

$$\hat{A}_{ij} = \begin{cases} 0 & \text{w.p. } 1 - p \\ A_{ij}/p & \text{w.p. } p. \end{cases}$$

$$\begin{pmatrix} 5 & 3 & 3 & -2 & -7 & 8 & 9 \\ 1 & 2 & 2 & -17 & 1 & -8 & 9 \\ 21 & 41 & 22 & -2 & 0 & 0 & 0 \end{pmatrix} \rightarrow \quad (4)$$

$$\begin{pmatrix} 10 & 6 & 0 & 0 & -14 & 16 & 0 \\ 2 & 4 & 0 & 0 & 0 & -16 & 18 \\ 0 & 0 & 44 & 0 & 0 & 0 & 0 \end{pmatrix} \quad (5)$$

If $|A_{ij}| \leq 1$, **WHP**, $\|A - \hat{A}\|_2$ is small.

*** [Coming Attractions](#) See Achlioptas's talk.

“Exponential convergence” of Kaczmarz equation solver :

$$Ax = b$$

At iteration k : have x_k . Get x_{k+1} by adding to x_k the l.h.s. of any violated equation suitably scaled :

$$x_{k+1} = x_k + \frac{b_i - (A_{(i)} \cdot x_k)}{|A_{(i)}|} A_{(i)}.$$

Strohmer and Vershynin (2006): A is $m \times n$ with rank n . If at each step, i is chosen according to the length-squared distribution, then for x^* with $Ax^* = b$,

$$E|x_k - x^*|^2 \leq \left(1 - \frac{1}{R^2}\right)^k |x^* - x_0|^2,$$

where $R = \|A\|_F / \sigma_{\min}(A)$.

What is wrong with the length-squared distribution ?

An Example : A has the first $m - 1$ rows all equal and the last row orthogonal to them; all rows are of length 1. [Drineas, Vempala]

Best rank 2 approximation : A itself. **Error=0.**

Repeated sampling only yields the first vector.
Error $\not\sim O(\text{best error})$!!

Two Issues : **Relative Error** Get a low-rank approximation \hat{A} to A so that

$$\|A - \hat{A}\|_F \leq (1 + \epsilon) \|A - A_k\|_F.$$

(Recall : A_k best rank k approx to A .)

“Interpolative” approximation Get an \hat{A} which is in the span of at most s (s small) rows of A .

Deshpande, Rademacher, Vempala, Wong; Drineas, Mahoney, Muthukrishnan; Sarlos; Har-Peled; Martinson, Rokhlin and Tygert all address these questions.

COMING ATTRACTIONS **

Sarlos : Take s random (i.i.d.) linear combinations of the rows of A . Find best approximation \hat{A} to A in their span. Then with high probability :

$$\|A - \hat{A}\|_F \leq (1 + \epsilon) \|A - A_k\|_F,$$

provided $s \geq ck^2 \log m/\epsilon$.

One intuition : If one performs a random rotation of A on the left, one gets vectors all of roughly the same length. So

length-squared distribution \approx picking first s

More direct proof using classic and recent results on random projections in Sarlos. One issue : Random vectors are dense. But sparse random vectors with same properties recently developed....

Also tackles l_2 linear regression.

Martinson, Rokhlin, Tygert : Independent development on similar lines. But $s \approx k + 20$. (No oversampling !). But weaker error bounds of the form (for $m = n$) :

Error in spectral norm at most $O(kn)\sigma_{k+1}(A)$.
Much better Empirical results.

Tensors

Max-3-SAT : Given a Boolean CNF formula with 3 literals per clause, find an assignment to the variables satisfying as many clauses as possible. x_1, x_2, \dots, x_n 0-1 variables. Let $S = \{(x_1, x_2, \dots, x_n, 1 - x_1, 1 - x_2, \dots, 1 - x_n) : x_i \in \{0, 1\}\}$. Max-3-SAT can be formulated as :

$$\text{Max}_{y \in S} : \sum_{i,j,k} A_{i,j,k} y_i y_j y_k.$$

Rank 1 3-tensor : Outer product of 3 vectors
: $u \otimes v \otimes w = (u_i v_j w_k)$.

Low Rank Approximation (LRA) of tensors : Approximate by a sum of a small number of rank 1 tensors. If we can find a LRA B , replace A by B ; solve exploiting the low rank of B .

Existence, Computation ??? — Golub and Lim; SATURDAY

Existence Lemma For any r -tensor A , $\epsilon > 0$, there exist $k \leq 1/\epsilon^2$ rank-1 tensors, B_1, B_2, \dots, B_k such that

$$\|A - (B_1 + B_2 + \dots + B_k)\|_2 \leq \epsilon \|A\|_F.$$

Computation Theorem For any r -tensor (r fixed) A , $\epsilon > 0$, we can find k rank 1 tensors B_1, B_2, \dots, B_k , where $k \leq 100/\epsilon^2$, in time $(n/\epsilon)^{O(1/\epsilon^4)}$ such that with high probability we have

$$\|A - (B_1 + B_2 + \dots + B_k)\|_2 \leq \epsilon \|A\|_F.$$

— de la Vega, K., Karpinski and Vempala

Notation : $\|A\|_2$ is the spectral norm =

$\text{Max}_{u,v,w} A(u, v, w) = \sum_{ijk} A_{ijk} u_i v_j w_k$ over all unit length vectors.

Finding LRA for 3-tensors Enough to find u, v, w to maximize

$$A(u, v, w) = \sum_{ijk} A_{ijk} u_i v_j w_k.$$

Point 1 If u, v are known,

$$w = A(u, v, \cdot) = \sum_{ij} A_{ij\cdot} u_i v_j \quad (6)$$

suffices.

Point 2 We can **estimate** the sum in the r.h.s. of (6) if we have just $O(1)$ terms picked according to the **length-squared distribution**. For this, need only $O(1)$ u_i, v_j !!

Point 3 We can enumerate all possible values of these $O(1)$ u_i, v_j and find all candidate w .

Point 4 We can check which candidate w is best by finding **maximum eigenvalue** of each **matrix** $A(\cdot, \cdot, w)$!!